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DigiTwin and proven dike strength

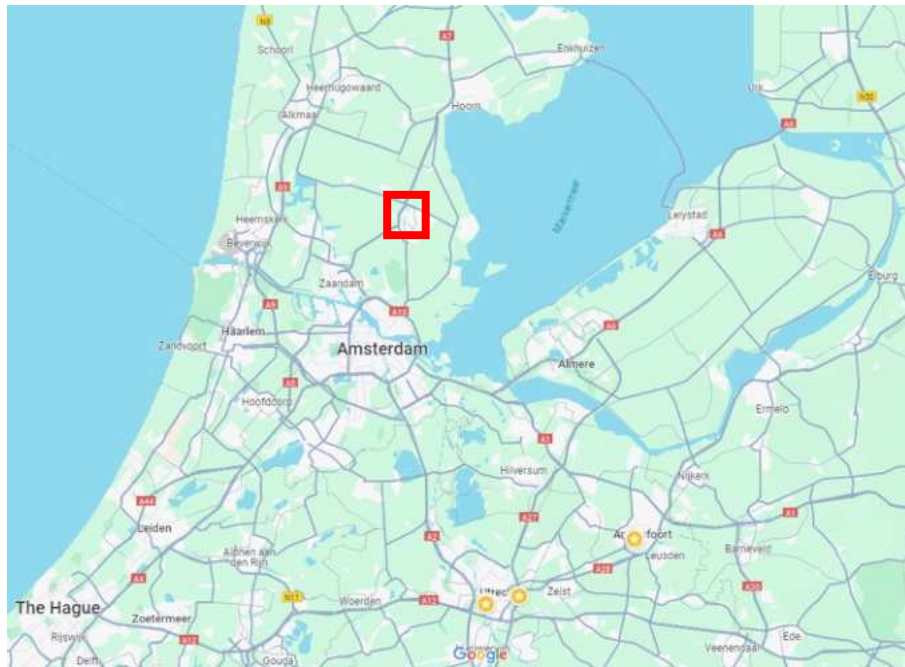
DigiShape day | Dike Monitoring and AI

Anton van der Meer, Teun van Woerkom, Kin Sun Lam
in cooperation with Hoogheemraadschap Hollands Noorderkwartier



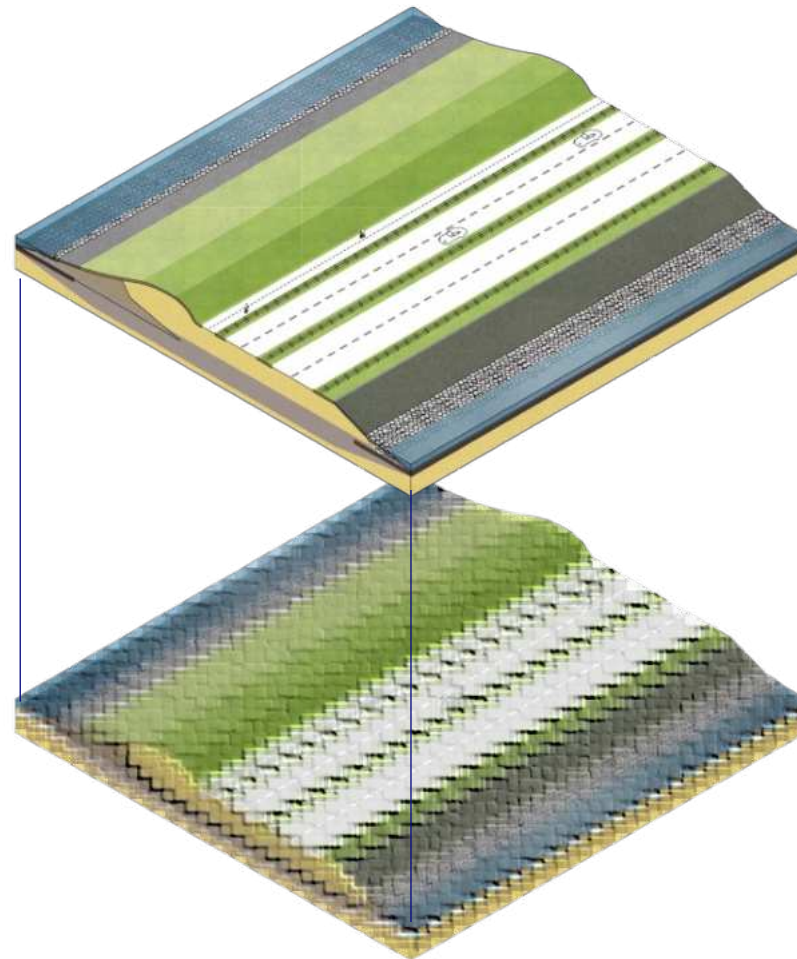
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What is a digital twin?

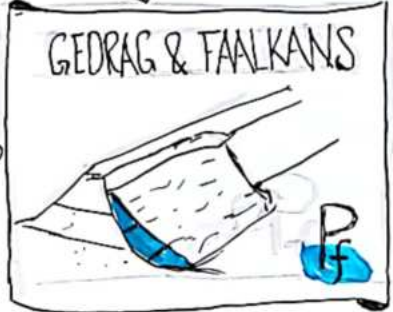
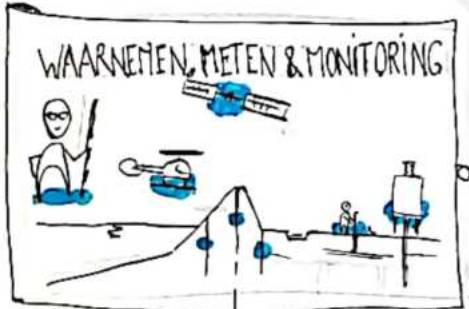
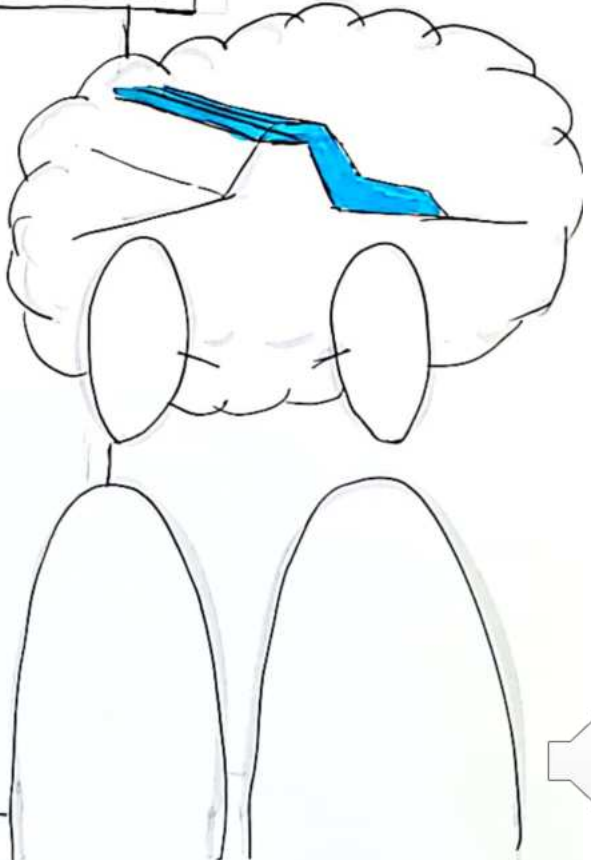
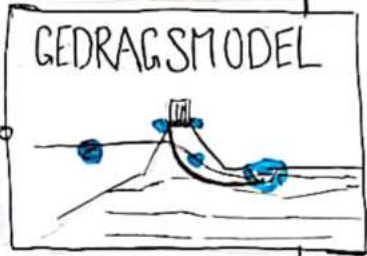
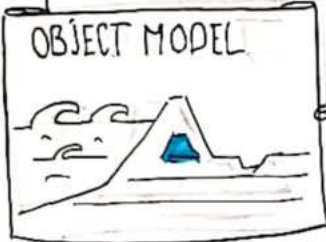
A digital twin is a **dynamic, virtual representation** of a **physical asset, product, process, or system**.



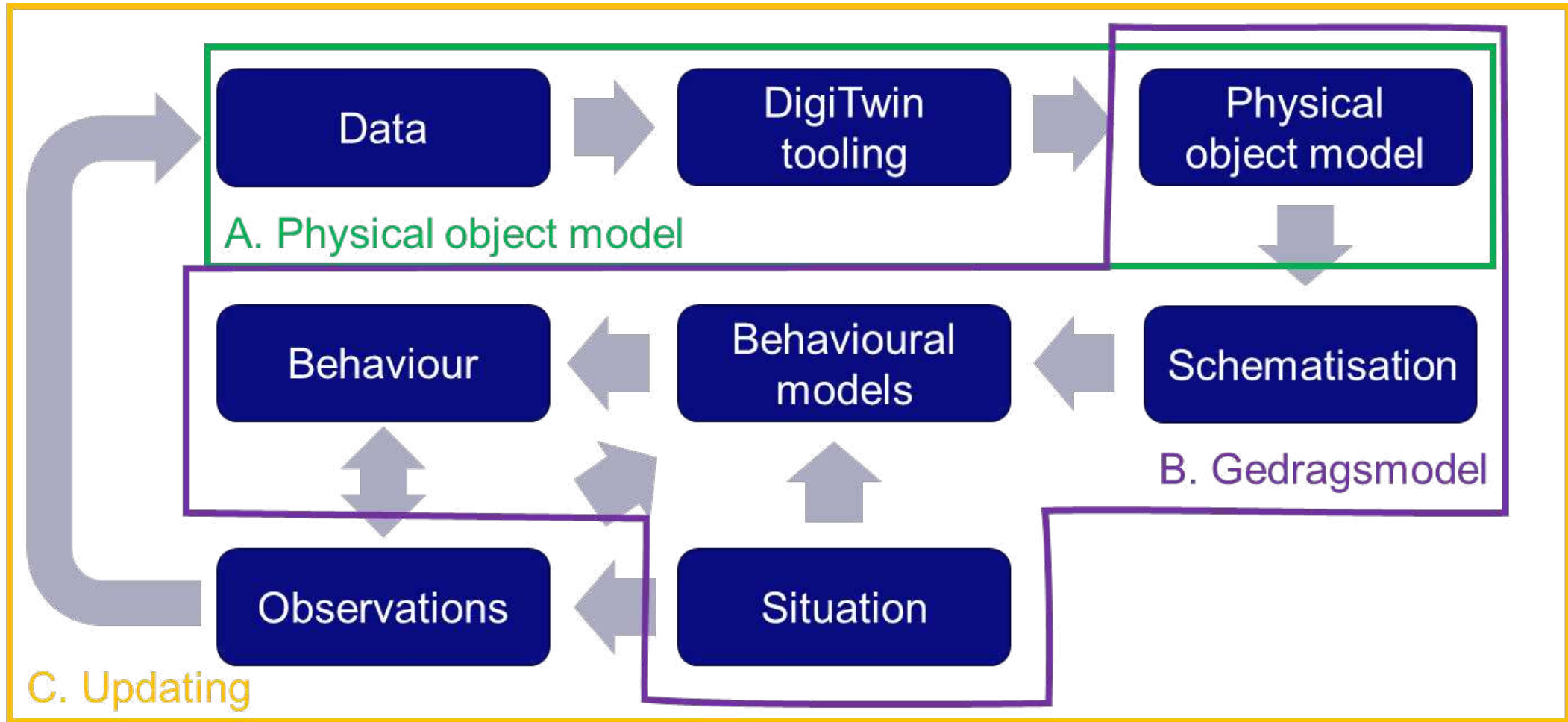
Physical model

Virtual model

DIGITAL TWIN WATERKERINGEN

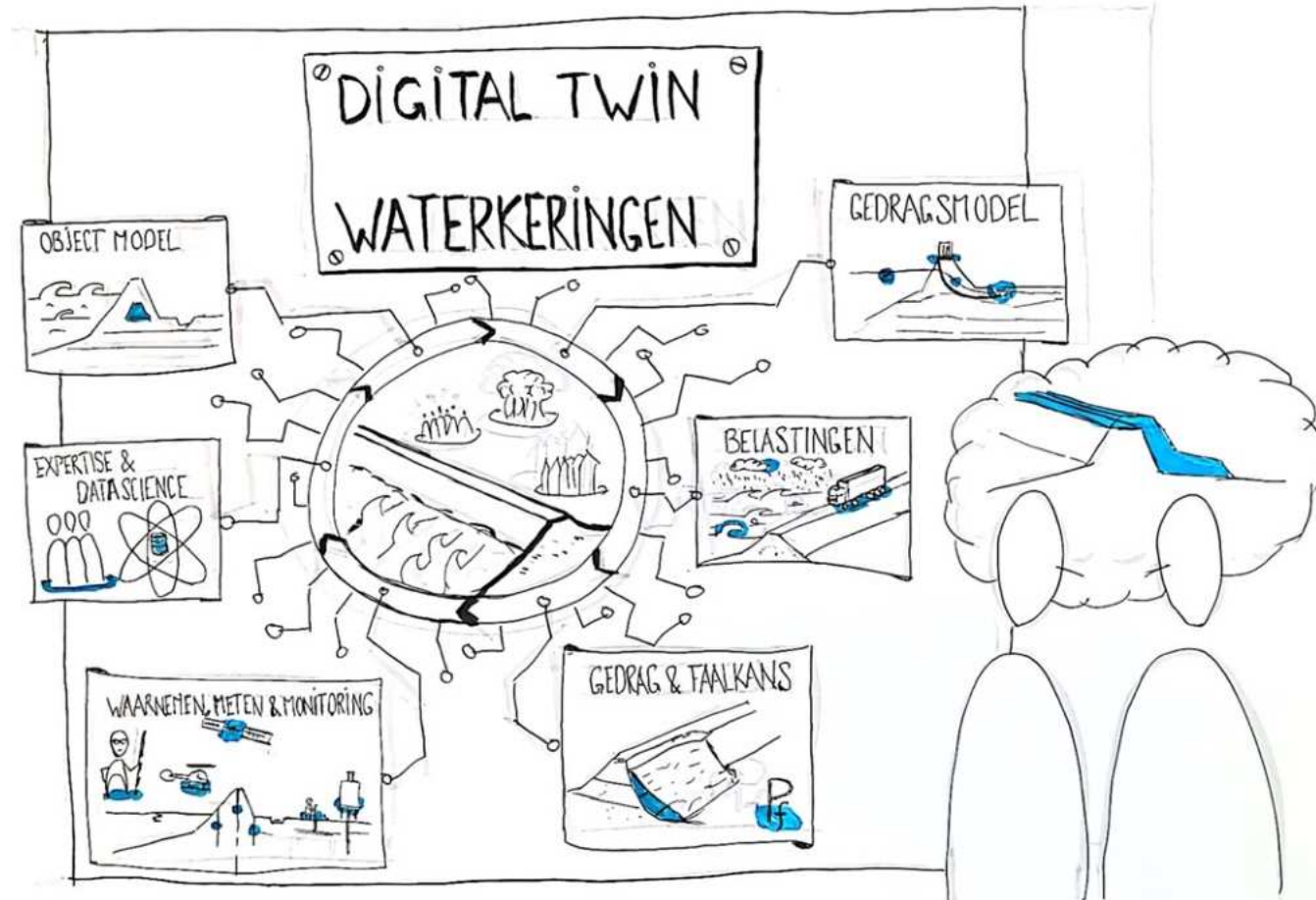


DigiTwin framework



The role of monitoring data and science/AI in DigiTwin

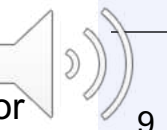
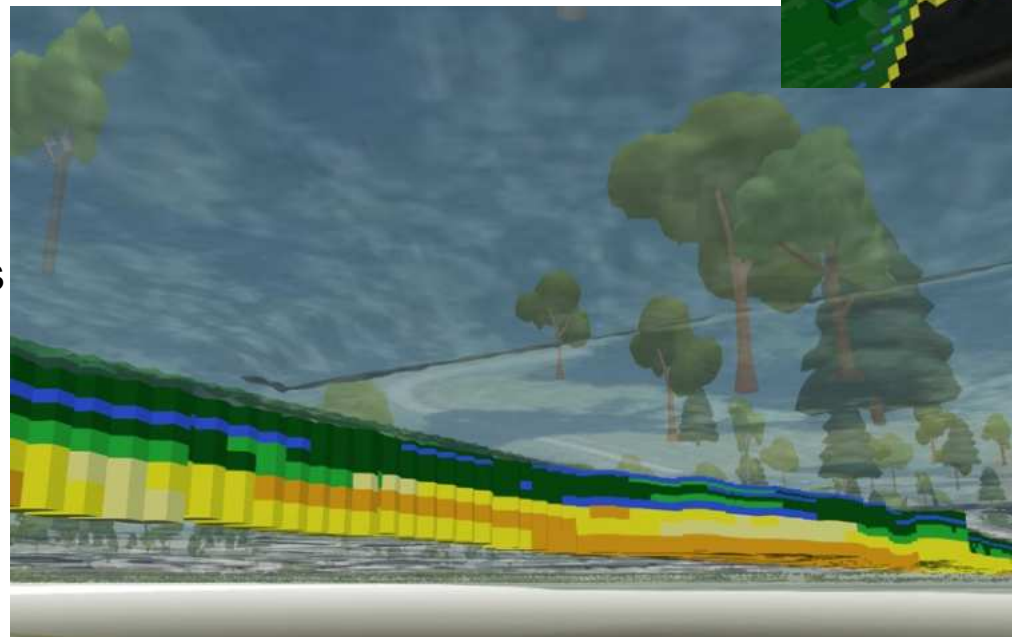
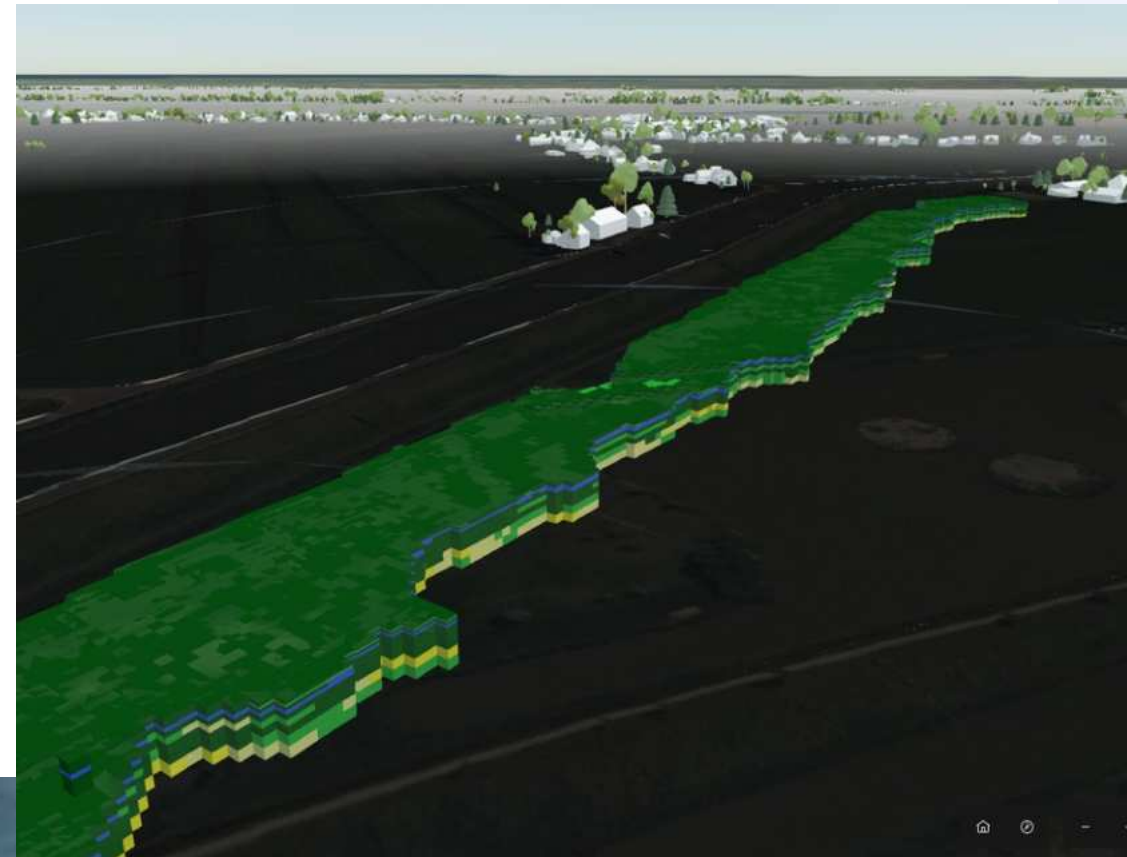
- Monitoring, observations and sensing technology are input for the existing models
 - Also indirect data, like remote sensing
- Data science/AI supports experts to link monitoring, observations and sensing technology with the existing models
 - Expertise still needed for creativity, domain expertise and critical thinking
- Updating the models with monitoring, observations and sensing technology
- AI in decision support



Example: subsoil modelling

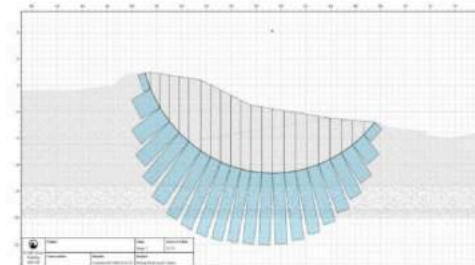
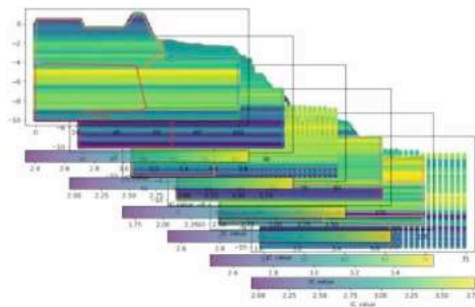
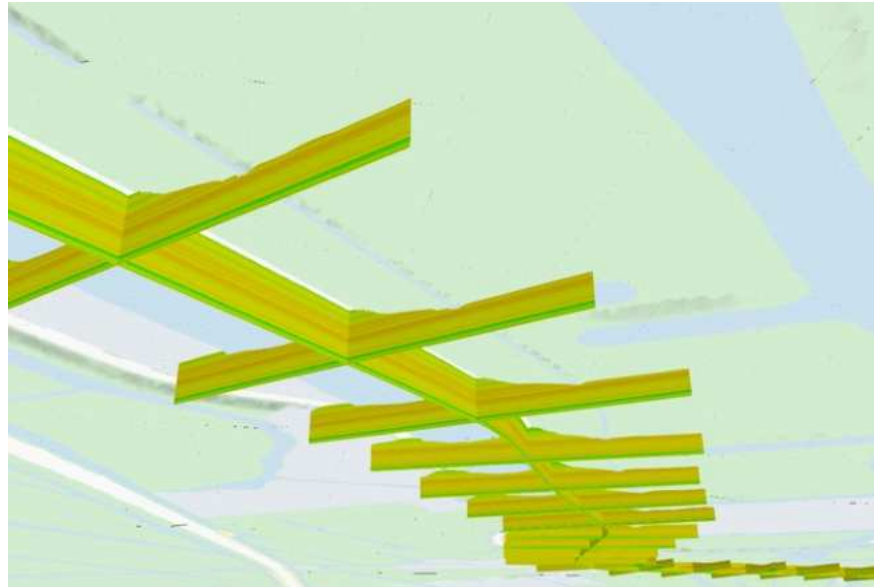
- Data:
 - Boreholes
 - CPTs
 - EM measurements
 - (InSAR)
- Data Fusion:
 - ML algorithms
- Subsoil Model

- Updating with new CPT's and borholes



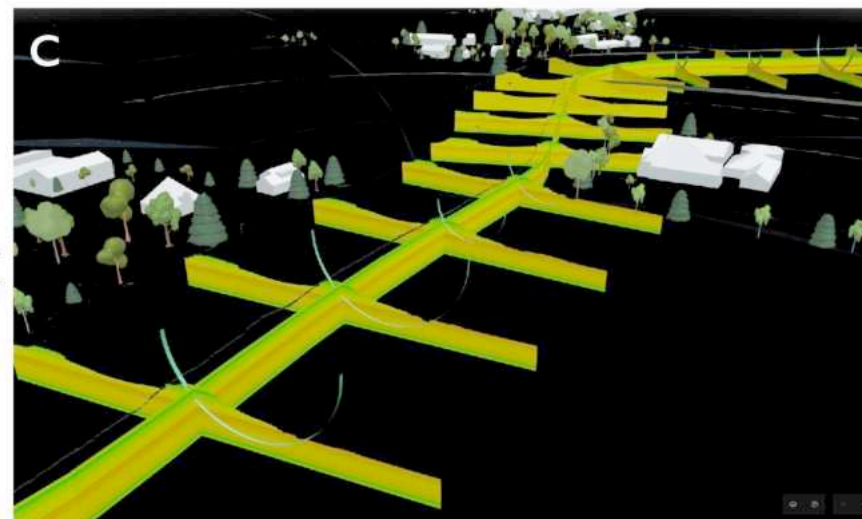
Example: subsoil modelling

- Subsoil Model
- Behaviour
 - Squeezing
 - Stability

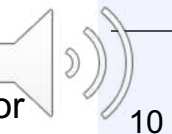


A


B

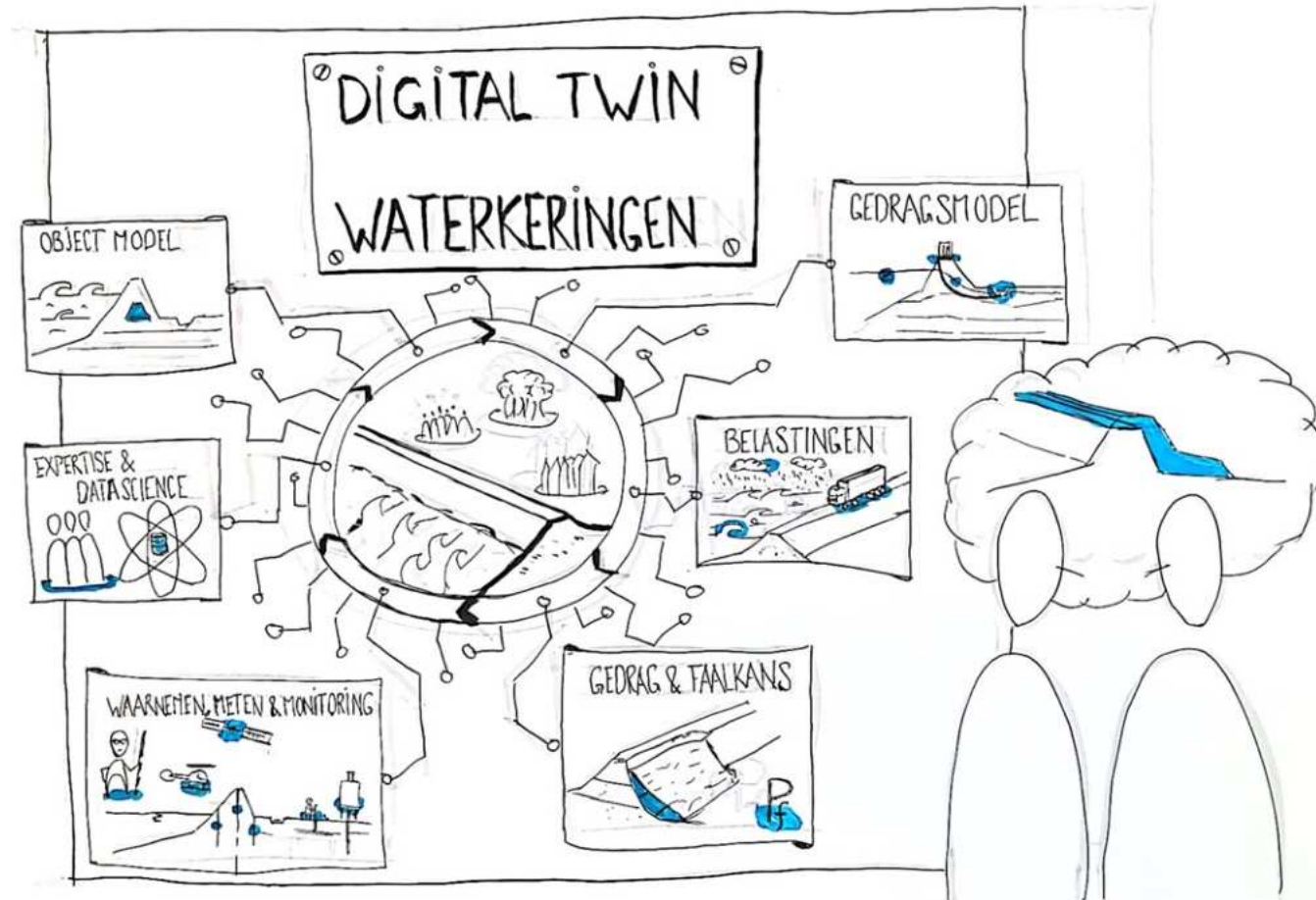


C



Case Purmer – Proven dike strength with groundwater monitoring

- Earlier pilot: real time stability with groundwater monitoring in a operational system
- Goal: Updating the probability of failure with groundwater monitoring
- Forecast/hindcast of the groundwater levels 
- D-Stability/Probabilistic Toolkit



Earlier pilot: real time stability with groundwater monitoring in a operational system



> Kaartlagen

Waterkeringen

- Status
- DAM-Live

Failuremechanism

Combinatie faalmechanismen

Belastingen

Dispectie

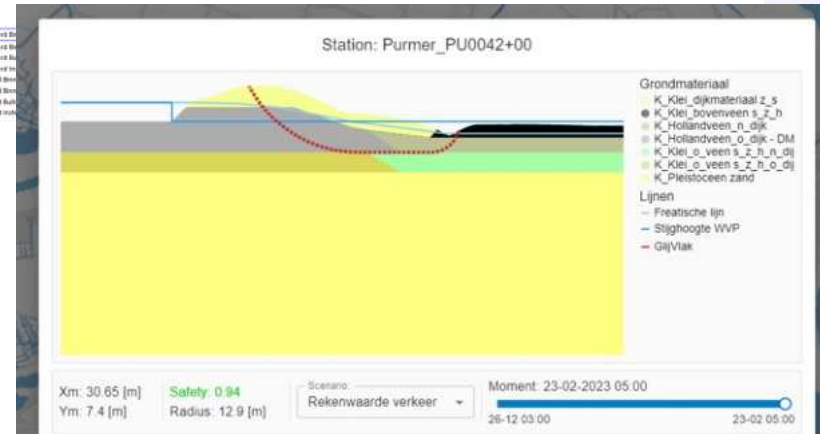
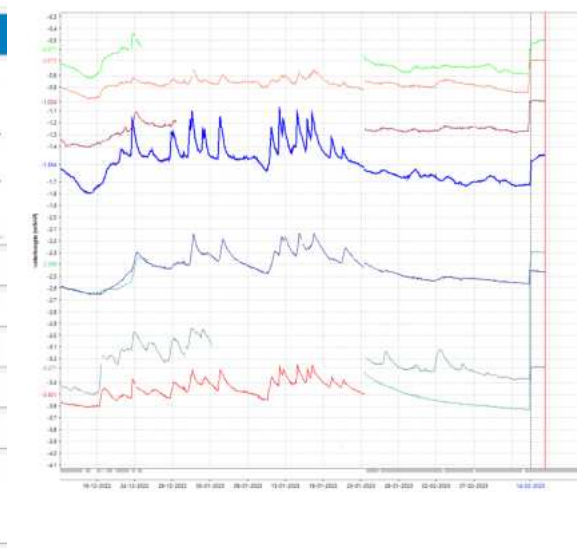
Status maatregelen

Extra kaartlagen

Overstromingsscenario's

Achtergrond

- Topografie water
- Luchtfoto



Station: Purmer_PU0042+00

Veiligheidsfactor:
(scenario: Rekenwaarde verkeer)

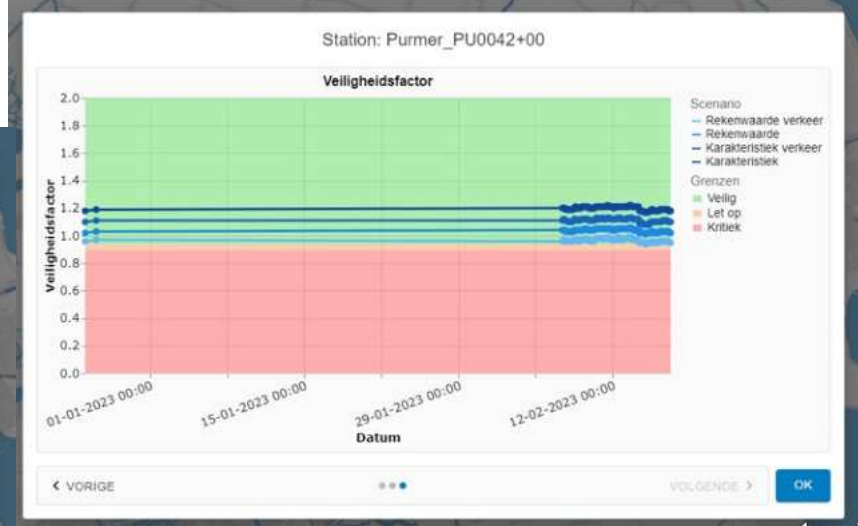
0.95

Minimale veiligheidsfactor afgelopen 48 uur:
(scenario: Rekenwaarde verkeer)

0.94

Status: **Veilig**

< VORIGE VOLGENDE > OK



Visualisation in HKV Continu Inzicht Dashboard

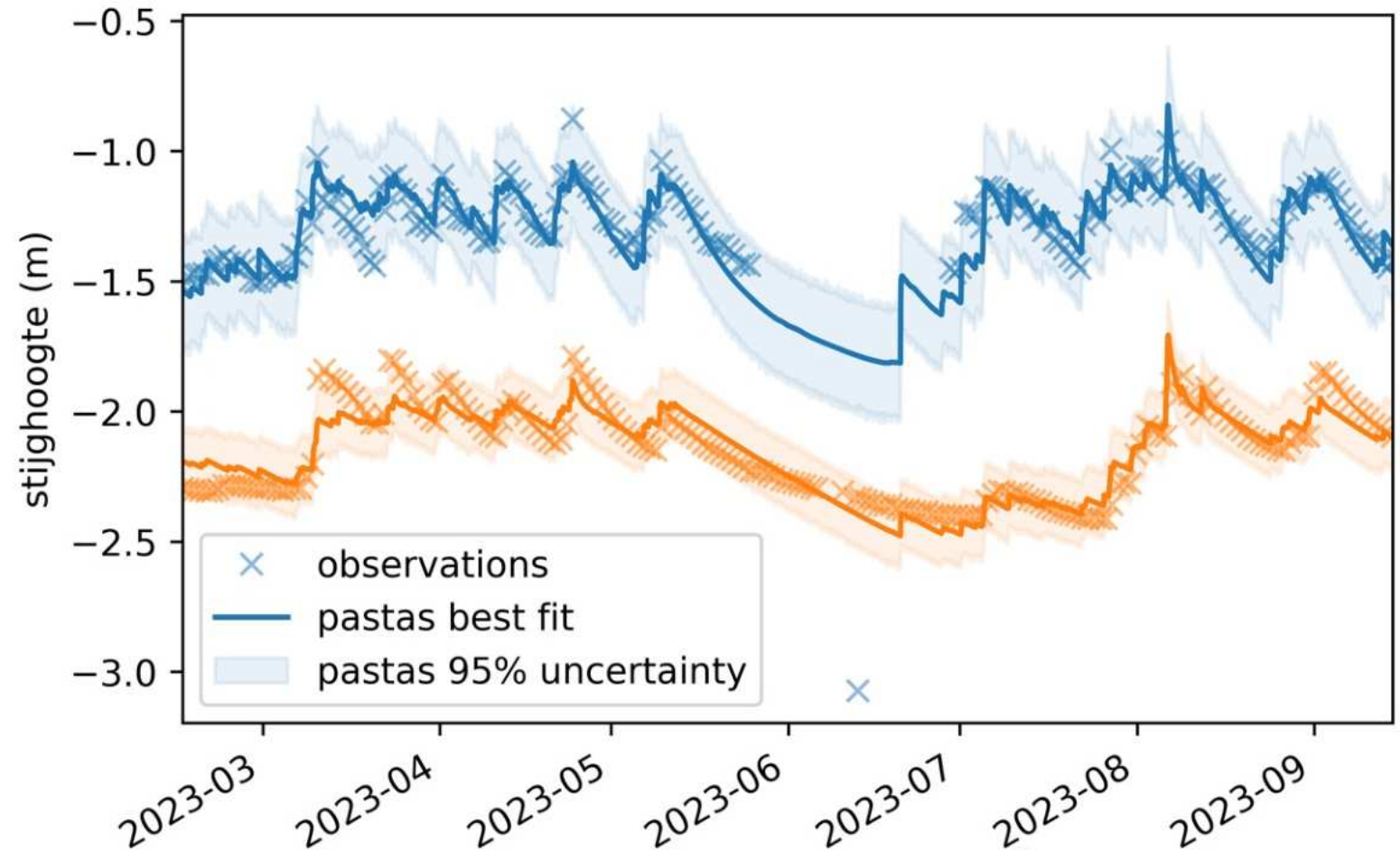


Pilot case Purmerend
Data/results just for demonstration purpose

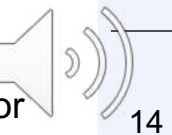
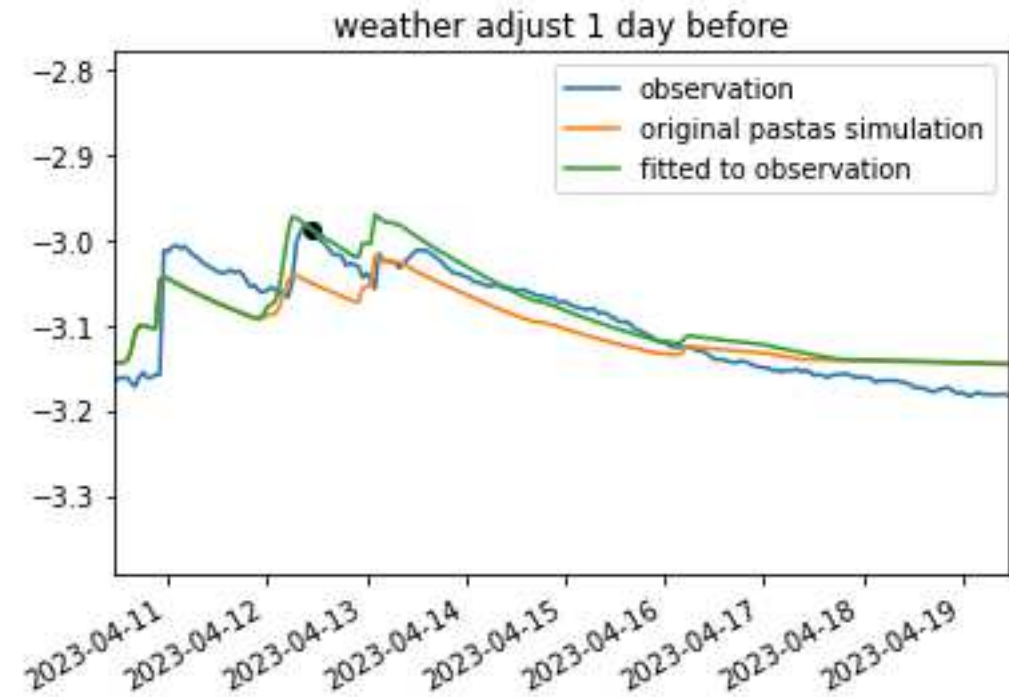
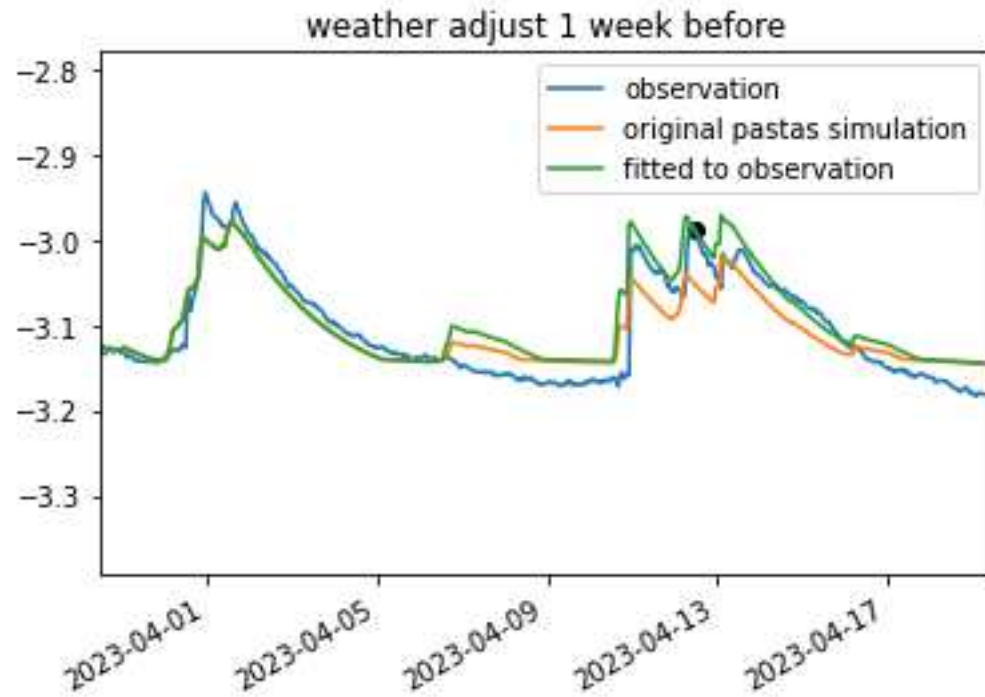
Forecast/hindcast of the groundwater levels



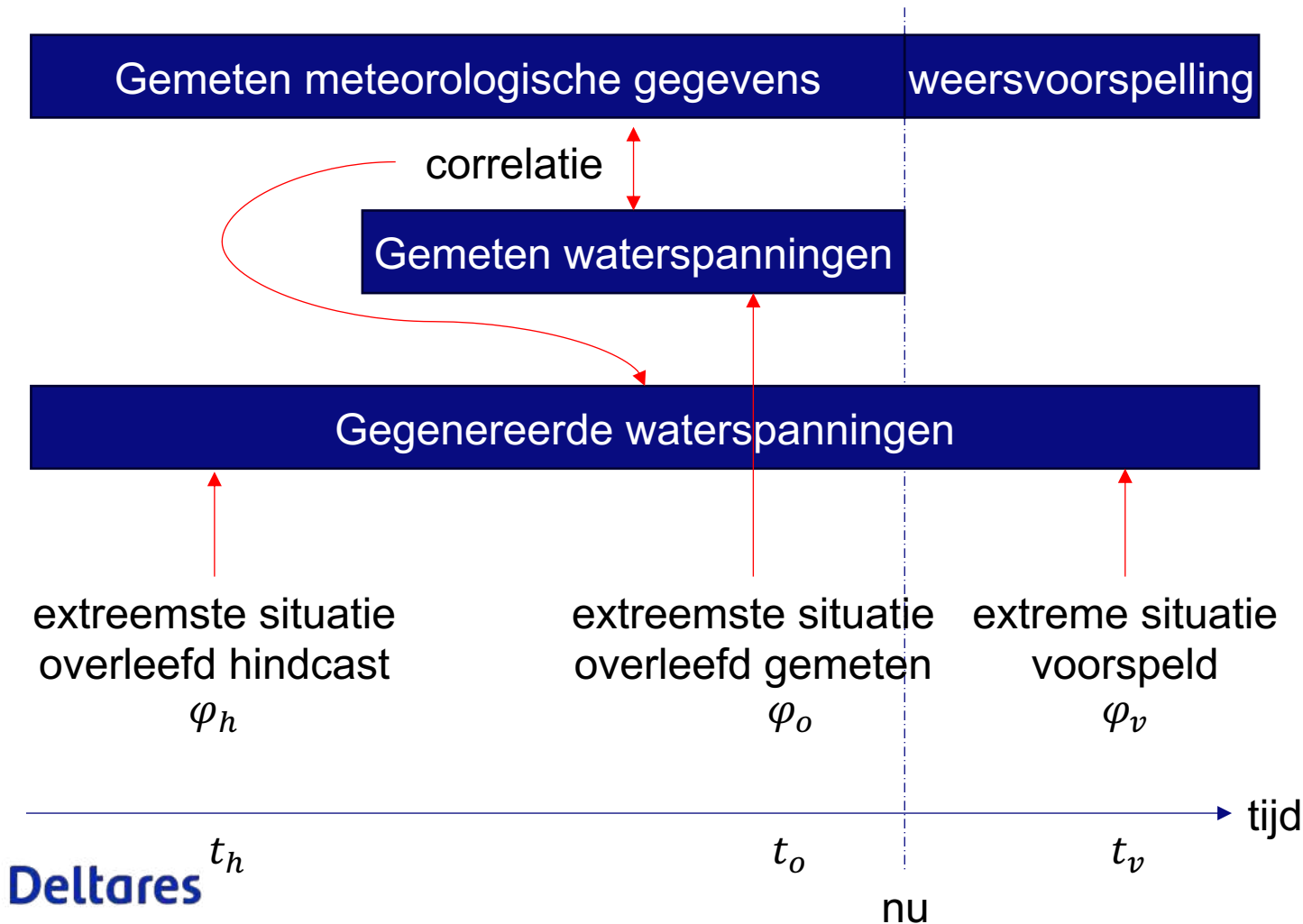
- Input time series:
 - precipitation
 - Evaporation
 - Grondwater level in gauges
- Output time series:
 - Best fit
 - Reliability interval



Forecast/hindcast of the groundwater levels



Updating failure probability



$$Z = \text{Sterkte} - \text{Belasting}$$

$$Z < 0 \rightarrow \text{falen}$$

$$P(Z(\varphi_v) < 0)$$

Updating:

$$P(Z(\varphi_v) < 0 | Z(\varphi_o) \geq 0)$$

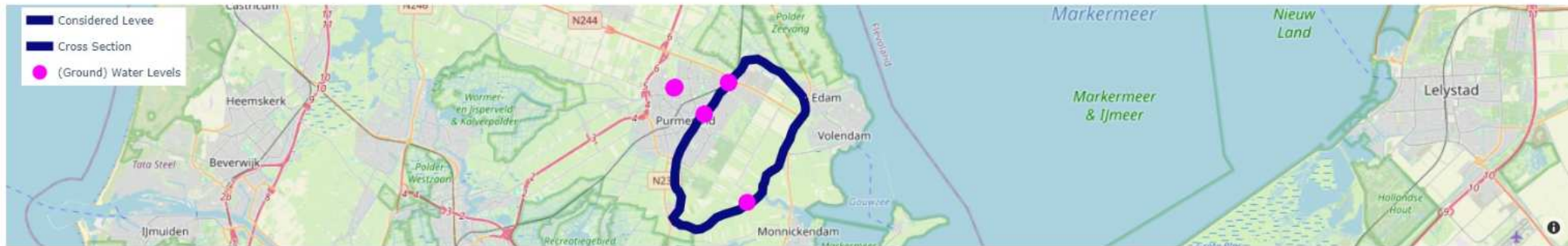
$$P(Z(\varphi_v) < 0 | Z(\varphi_h) \geq 0)$$



Stability and probability of failure

Dike Monitoring Purmer

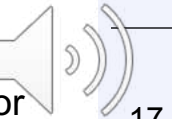
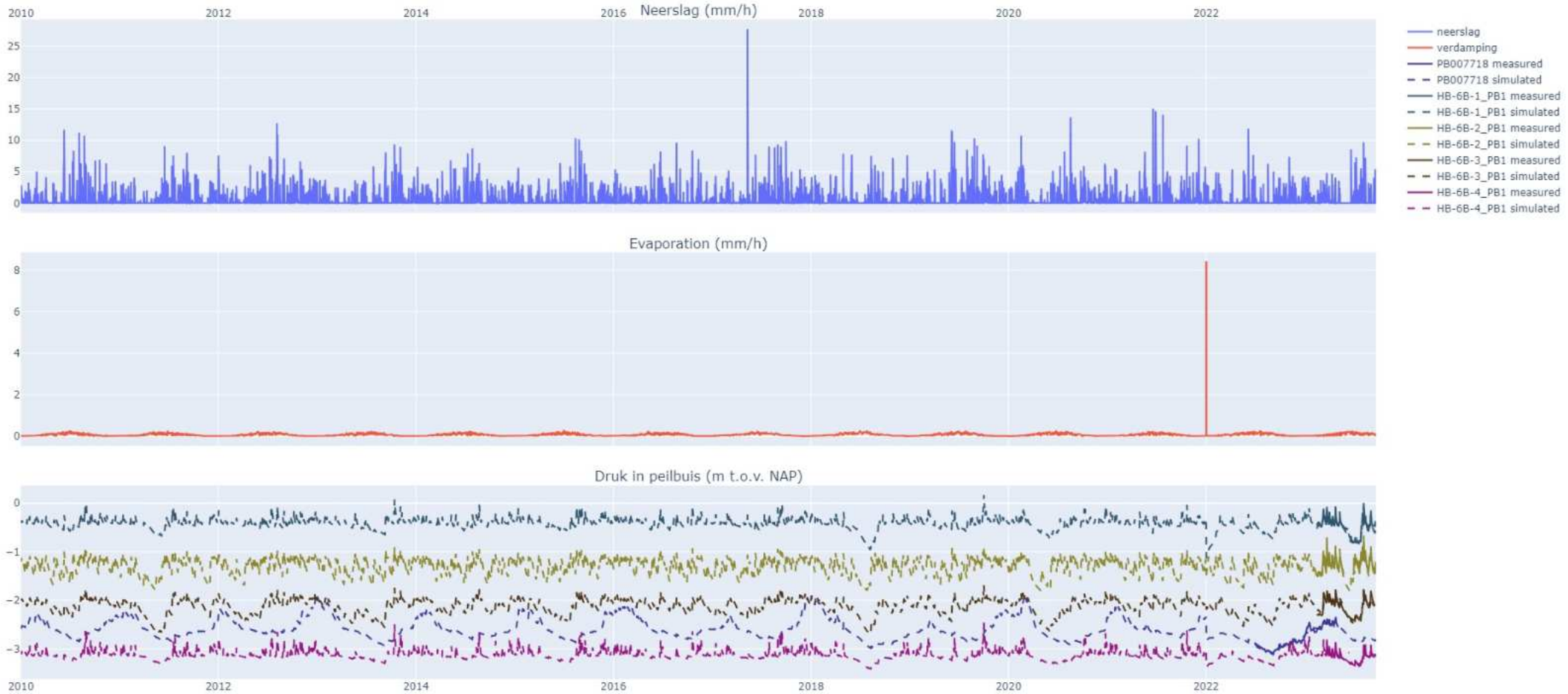
Large Map Time Series Cross Section



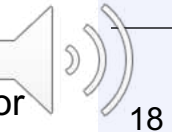
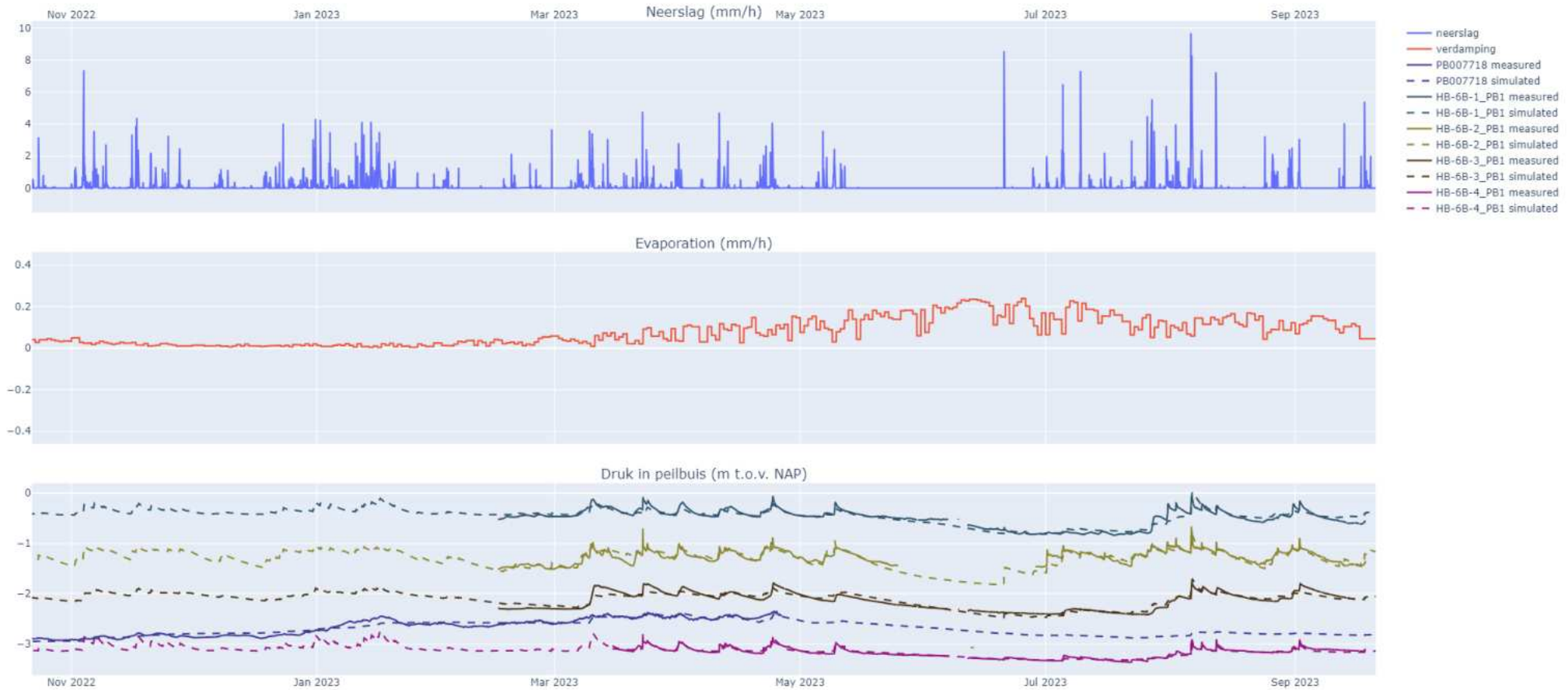
This dashboard presents the stability of a cross-section of the Purmer levee. The location of the cross-section is given on the map above. The stability is dependent on the pore water pressures in the levee and subsoil. Those are described by the hydraulic head. We distinguish between the phreatic line (PL) and a headline (HL) in the aquifer. The PL and HL are measured from 2022 with 5 different stand pipes, shown on the map. The PL and HL vary with varying surface water level (canal and polder) and effective precipitation (rain and evapotranspiration). Since the polder level and the canal level are controlled and fixed the HL and PL can be correlated with the effective precipitation.



Stability and probability of failure



Stability and probability of failure



Stability and probability of failure

Stability

The stability is time dependent and the main time dependent drivers controlling the variation in stability are the pore water pressures and external loads (such as traffic loads). Here the stability is calculated based on three scenarios of PL and HL. The first is the highest measured PL (based on the inner crest stand pipe) with the corresponding HL. The second the highest hindcasted PL with the corresponding HL. And the last the PL and HL with a 1000 years return period. The corresponding dates are shown in the table below. The stability factors are calculated with D-Stability using D-GEOLib. The probability of failure for the scenario "1000 years return period" is calculated with the Probabilistic Toolkit.

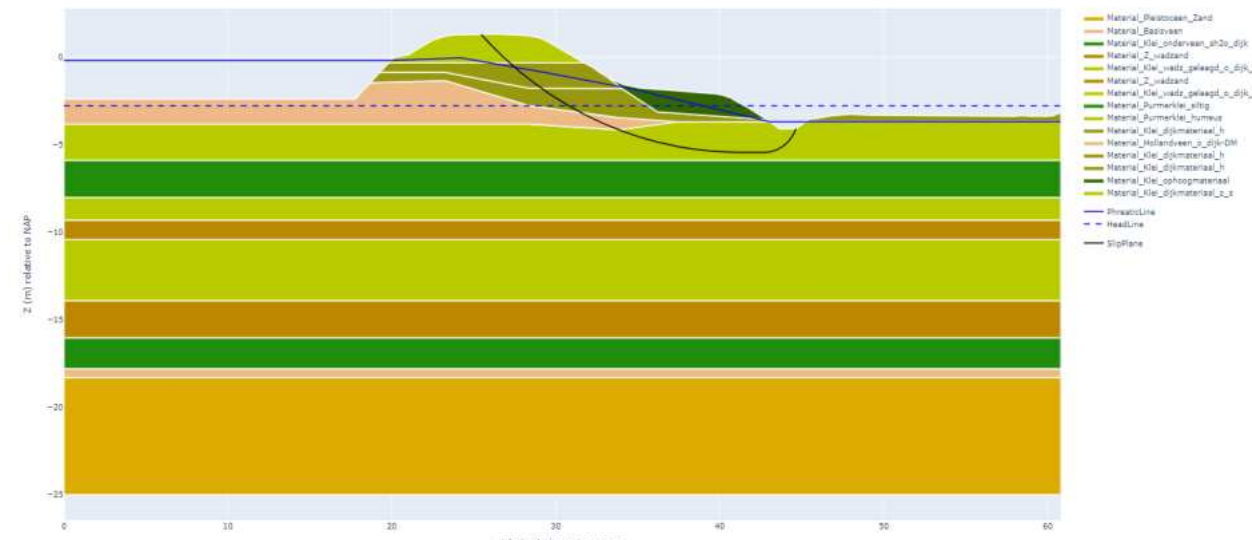
| Scenario | Date | Stability Factor | Probability of Failure | Convergence (prob) |
|---|---------------------|--------------------|------------------------|--------------------|
| maximum measured (until 18 Sept 2023) | 2023-08-06 06:00:00 | 1.670710968666013 | nan | nan |
| maximum hindcasted (until 20 sept 2023) | 2019-10-01 22:00:00 | 1.4246732912121818 | nan | nan |
| 1000 year return period (extrapolated) | None | 1.300366398512559 | 0.385365139255325 | 0.997170647182928 |
| 10 year return period (idf) | None | 1.3048554703417017 | nan | nan |
| 100 year return period (idf) | None | 1.2813114291905716 | nan | nan |
| 1000 year return period (idf) | None | 1.2485670600595935 | nan | nan |
| Winter 2023 | None | 1.4005026534881904 | nan | nan |

Details per Scenario

Choose below the pore water pressure scenario to be shown in the graph.

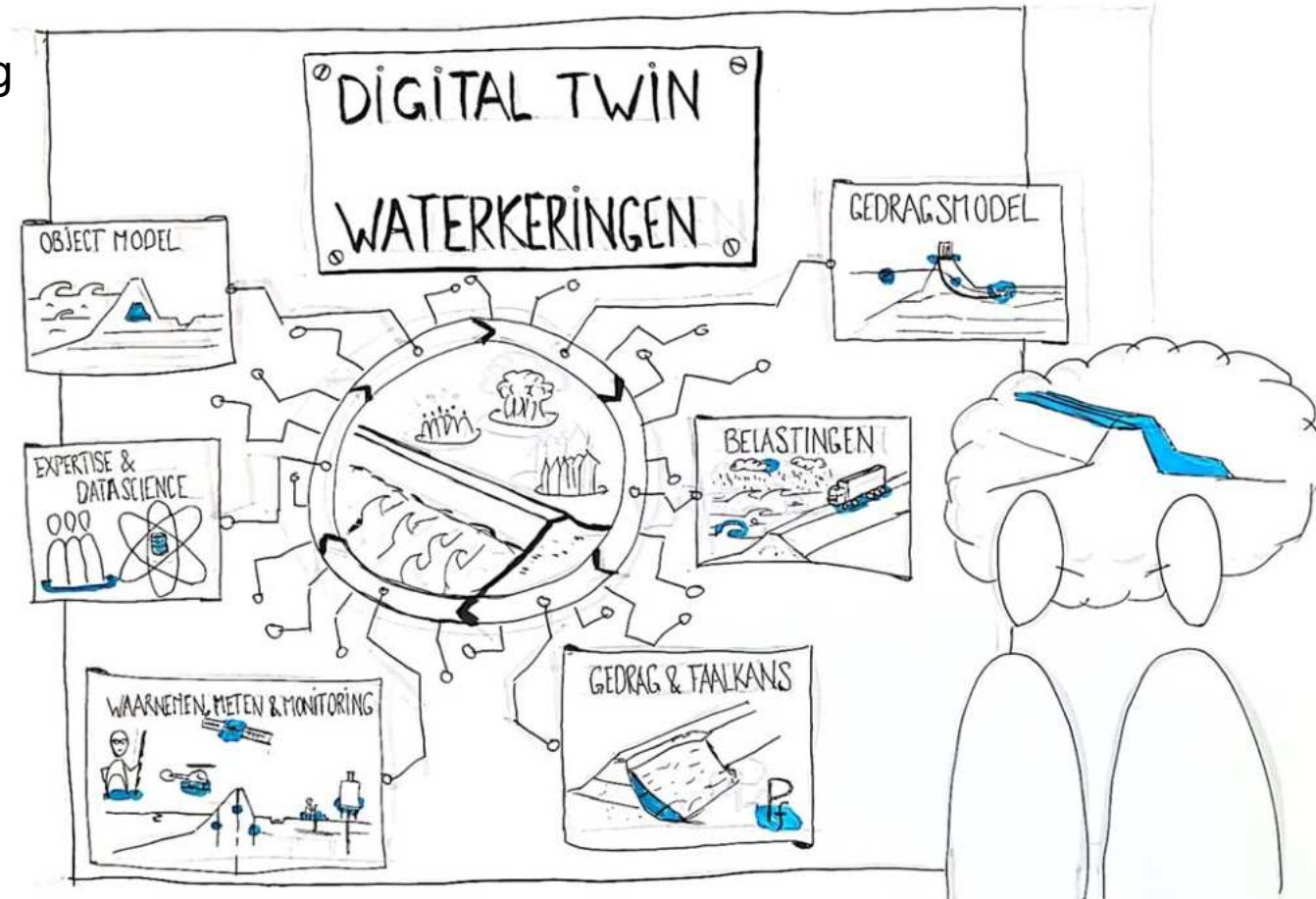
Winter 2023

Cross-Section



Conclusions

- Real time stability with groundwater monitoring
- Forecast/hindcast of stability with forecast/hindcast groundwater time series
- Updating the probability of failure with groundwater monitoring
- Possibilities to improve the models and predictions with more and better data (monitoring), other AI and data science techniques.



Contact

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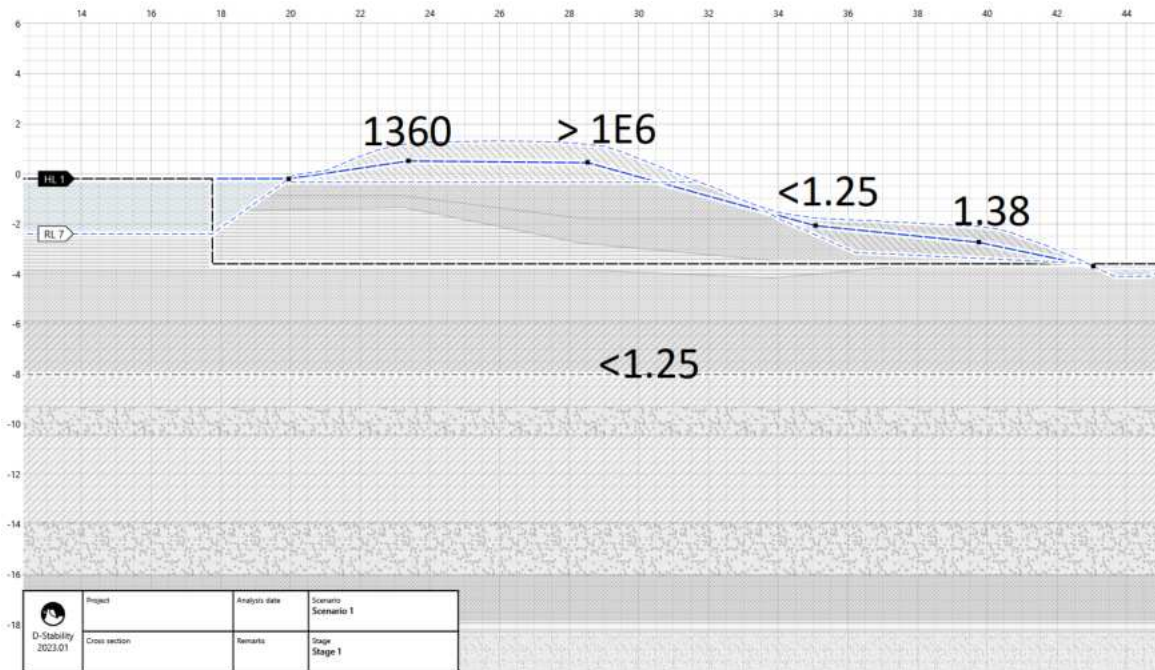
 info@deltares.nl

 [@deltares](https://www.instagram.com/deltares)

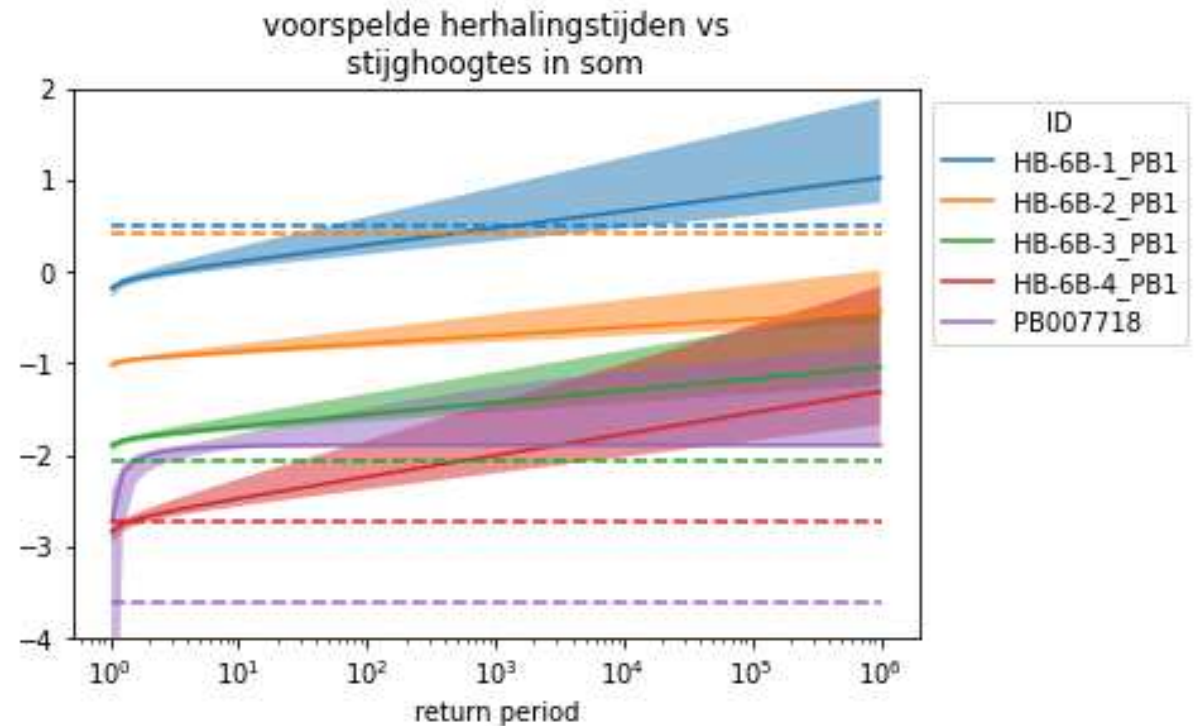
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Comparison with assessment



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Return periods

The hindcasted heads are extrapolated into heads with a 2, 10, 20, 100, 200, 1000 year return period. The result including the uncertainty band are shown in the graph below.

